

FE Simulation and Analysis of Shoulder Implants with Bone Remodeling



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Introduction

- Need for joint replacement

- Rheumatoid arthritis
- Traumatic injuries
- Rotator cuff tear

- Two types of arthroplasty

- Hemiarthroplasty - replacement of articular surface of the humeral head
- Total shoulder arthroplasty (TSR) – additional replacement of glenoid surface
- Prerequisite: intact rotator cuff
- Primary fixation: bone cement, screws, press fit
- Secondary fixation: bone ingrowth



Introduction

•Problems

- Prosthesis failure due to
 - Loosening
 - Inlay wear
 - Breaking of parts, especially screws

•Goals and investigations

- Know-How in the field of FE-analysis, 3D modelling, biomechanics and biogenic structures
- Virtual 3D surgery
- Highly accurate, realistic 3D modelling from CT to FE-analysis
- Optimal preoperative implant angle and position
- Statistic methods for evaluation and validation
- Patient-specific prosthesis design

Modelling

•CT segmentation

- Software: Mimics V13.0, 3matic V5.01
- Thresholding, Region grow
- Manual refinement
- Generation of 3D model
- STL-Export
- Import STL to 3matic V5.01
- Smoothing and compensate for defects

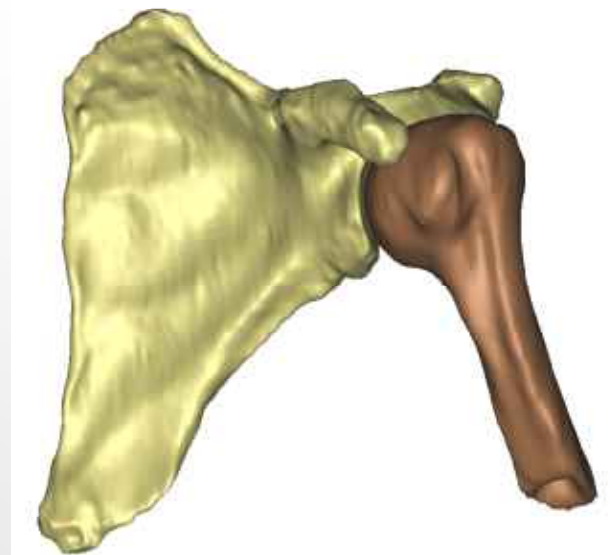


Fig. 3: Final 3D model after compensation

Fig. 1: Model after segmentation and 3D reconstruction

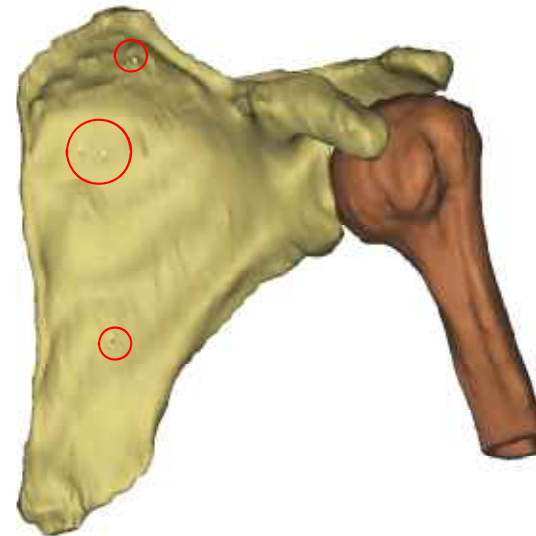
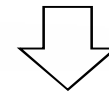
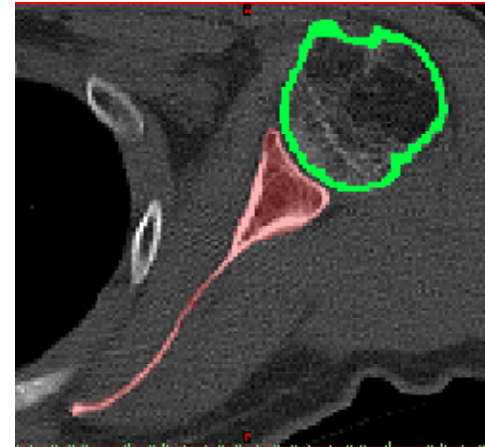
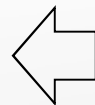


Fig. 2: Model after segmentation and 3D reconstruction



•3D modelling

- Positioning of implant (HAS-Prothesis - Stryker Howmedica Osteonics)
 - Reconstruction of anatomical or pathological state?
 - Definition of the neutral position
 - According to De Wilde et. al. (2010) using the inferior glenoid plane (API-plane) is most reliable and accurate
 - Inferior plane and scapular plane used for measurement of retroversion and inclination
 - Eventually repositioning due to anatomical issues (perforation)

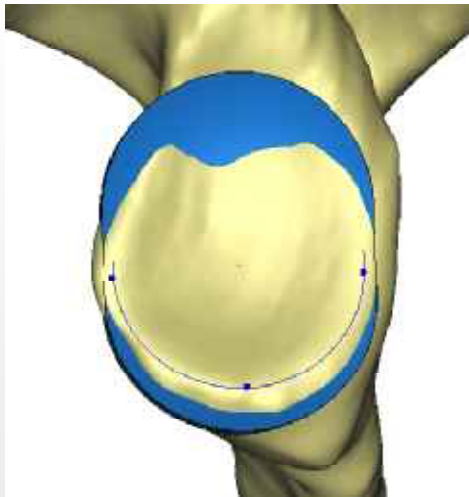


Fig. 4: Implant positioning by using the inferior glenoid plane

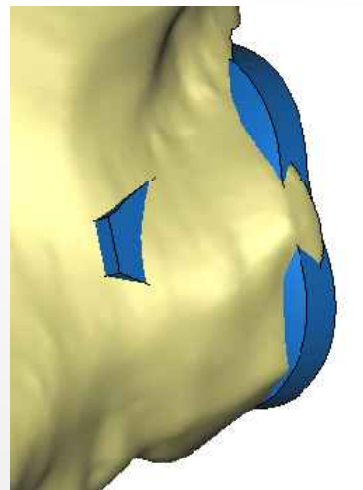


Fig. 5: Perforation of the scapular neck

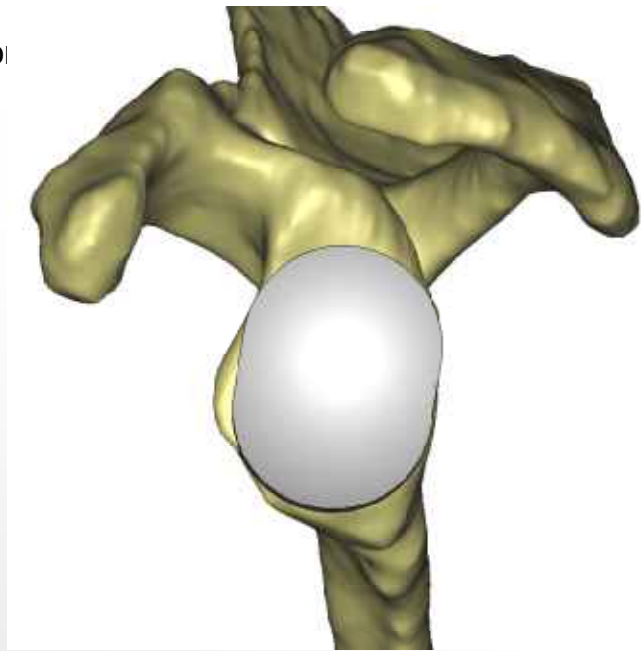


Fig. 6: Implant position after correction

• Virtual surgery procedure

- Preparation of glenoid surface with two tools (surface reamer and stencil)
- Modeling of bone cement
 - Ideal cement thickness ~1-1.5mm
 - Approach by using a constructed surface reamer and a stencil
- Boolean operation for bone cement
 - Cement block \ scapula
 - Cement block \ implant

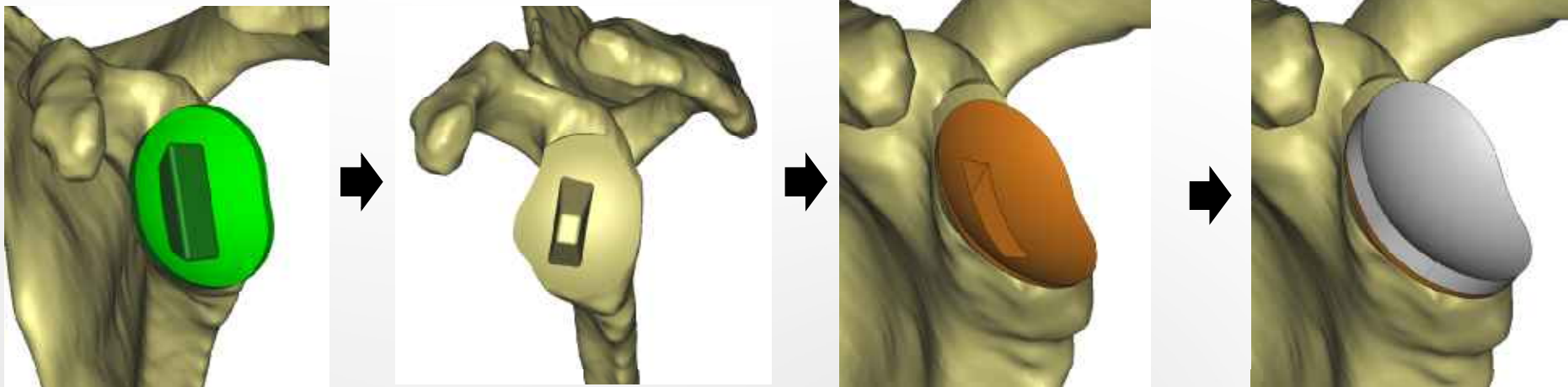


Fig. 7: Virtual surgery procedure

• Meshing

- Software: ICEM CFD
- Main steps
 - STL-Import & create geometry/topology
 - Define all curves of intersecting surfaces
 - Define body points in all parts and intersecting parts
 - Define meshing (max/min size, etc.) parameter

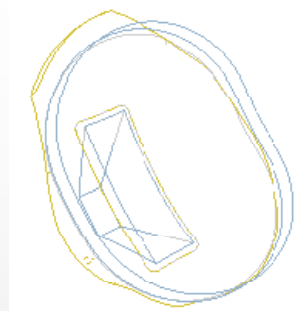


Fig. 8: Create geometry & intersecting surfaces

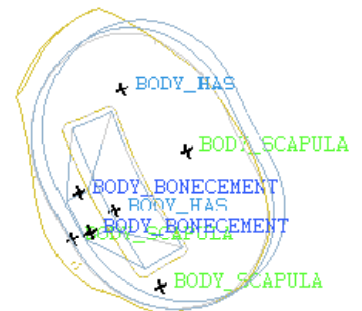


Fig. 9: Define body points

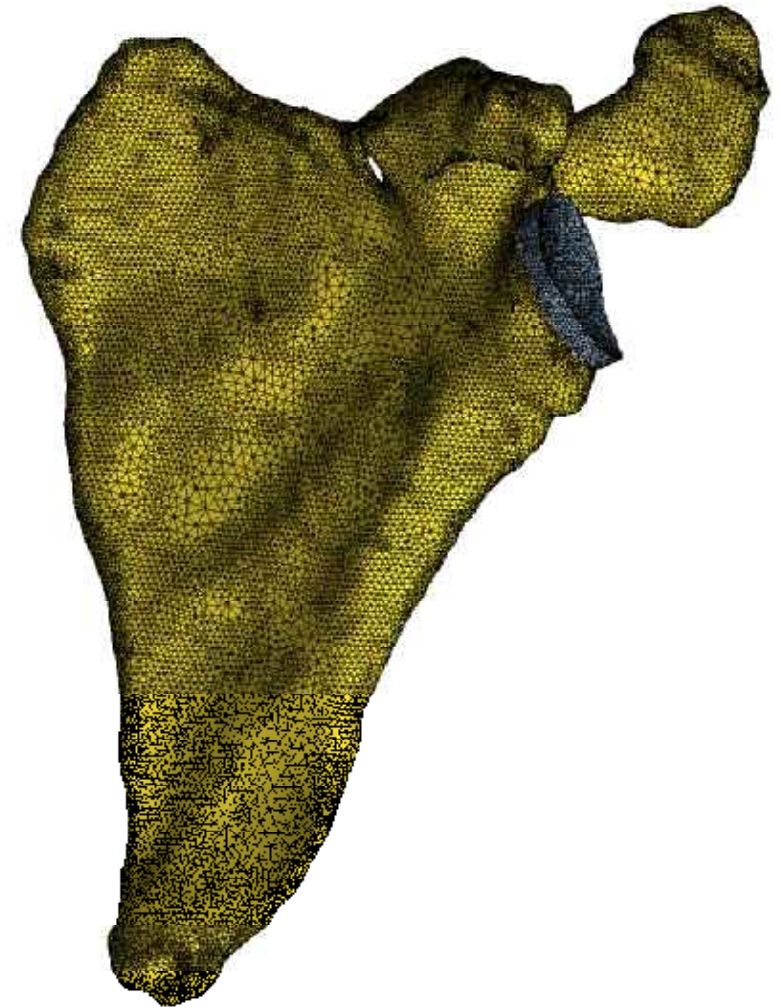


Fig. 10: Shoulder model – final mesh, ~380k elements

• Meshing

- Meshing by penetration
 - Boolean operations done by ICEM
 - Consistent nodes at part boundaries
 - Only for bonded contacts
- Meshing part by part
 - Boolean operations in 3matics
 - Contact definition with eg. friction coefficients for micromotion possible
- Check mesh for errors
- Smooth mesh concerning element quality
- Export mesh
- Import mesh to Ansys Classic and write CDB file for input to Ansys Workbench

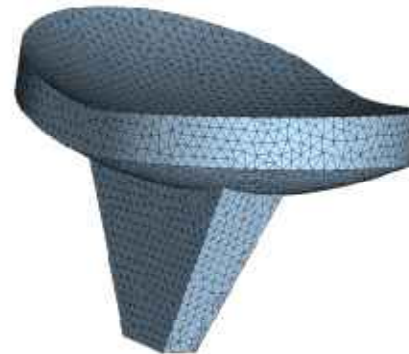


Fig. 11: Implant volume mesh

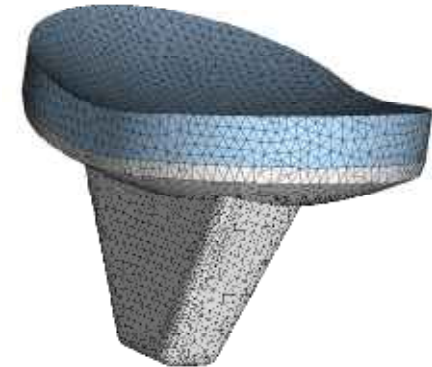


Fig. 12: Prosthesis & bone cement volume mesh

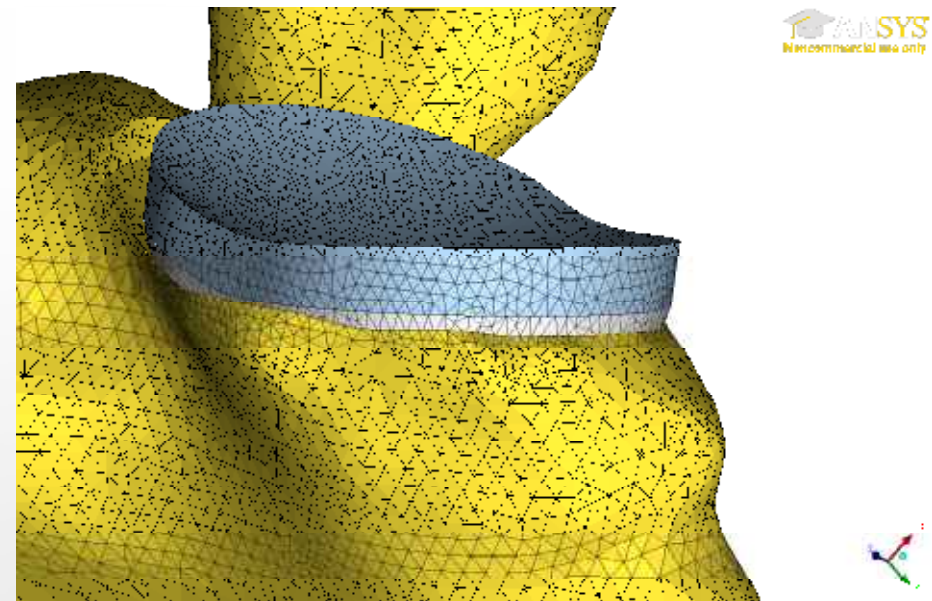


Fig. 13: Volume mesh of Implant, bone cement, and scapula

FEM – Definition

•FE-Modeller

- Define surfaces for bearing and loads
 - Flexion/Abduction (30° , 60° , 90° , 120° , 150° , 180°)
 - Positions according to Van der Helm (1994)
 - Entry surfaces of M.Trapezius and M.Rhomboideus

•Static Simulation

- Define material parameter

Material	Young's Modulus [MPa]	Poisson Ratio
Compacta	13.700	0.3
Bone cement	2.000	0.33
Polyethylene	500	0.3

- Define boundary conditions
 - Fixed bearing simulate M. Trapezius and M. Rhomboideus
 - Apply forces for flexion/abduction angle according to values and direction of Van der Helm (1994)
- Solve and evaluate Van Mises stress and deformation



Fig. 14: Define component for forces (30° flex.)



Fig. 15: Fixed bearing

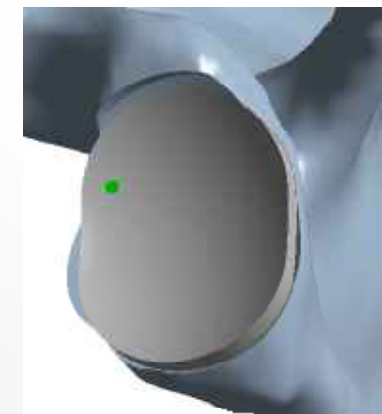


Fig. 16: Forces at 90° abd.

FEM – Results

• Validation

- Results are within the range of comparable studies from Terrier, Farron, Murphy, Prendergast and others.
- Reflect only a certain point in time

• Actual work

- Different angles and positions
- Probability of failure according to Murphy & Prendergast (2000)
- Result analysis and statistical evaluation

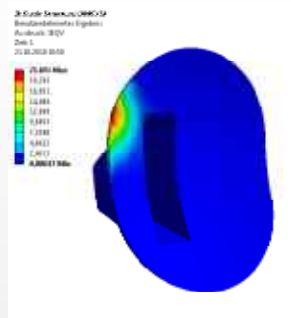


Fig. 17: Define component for forces (30° flex.)

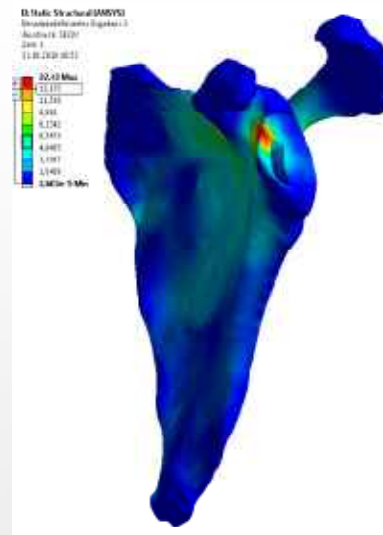


Fig. 18: Fixed bearing

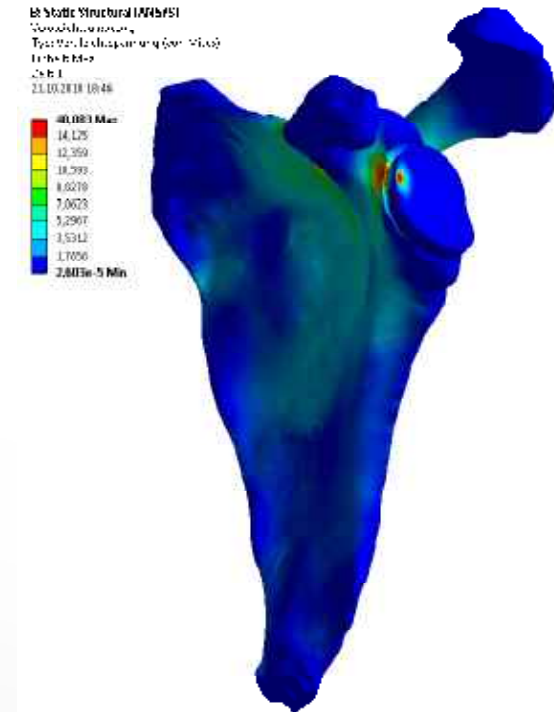


Fig. 19: Forces on 90° abd. and flex.

• Adaptive bone remodeling

- Wolff's law, a mechanical stimulus is responsible for bone remodeling, hence bone growth
- Formulation by Weinans (1992), Huiskes (1994) by using strain energy density (U) as the mechanical stimulus.

$$U = \frac{1}{2} \sigma \cdot \epsilon \quad \text{For one load step}$$

$$U_{TOT} = \frac{1}{n} \sum_{i=1}^n U_i \quad \text{For n-load steps, e.g. several humeral positions (abduction & flexion from } 30^\circ - 180^\circ)$$

- Local bone adaption function

$$\frac{d\rho}{dt} \begin{cases} B \left(\frac{U}{\rho} - (1+s)K \right) & \text{if } \frac{U}{\rho} > (1+s)K \\ 0 & \text{if } (1-s)K \leq \frac{U}{\rho} \leq (1+s)K \\ B \left(\frac{U}{\rho} - (1-s)K \right) & \text{if } \frac{U}{\rho} < (1-s)K \end{cases}$$

U... strain energy density
B... remodeling constant
K... reference stimulus
s... lazy zone factor

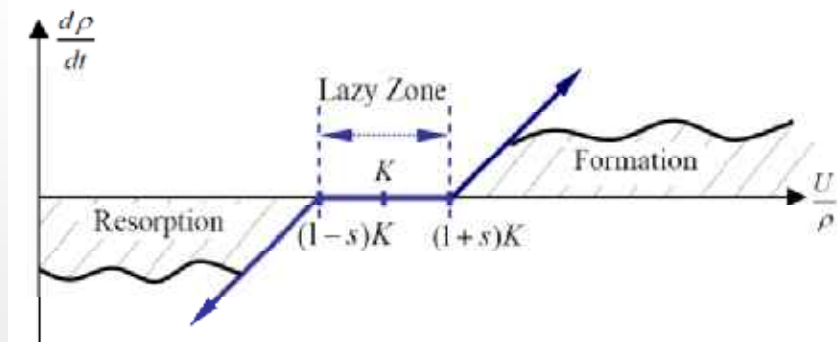
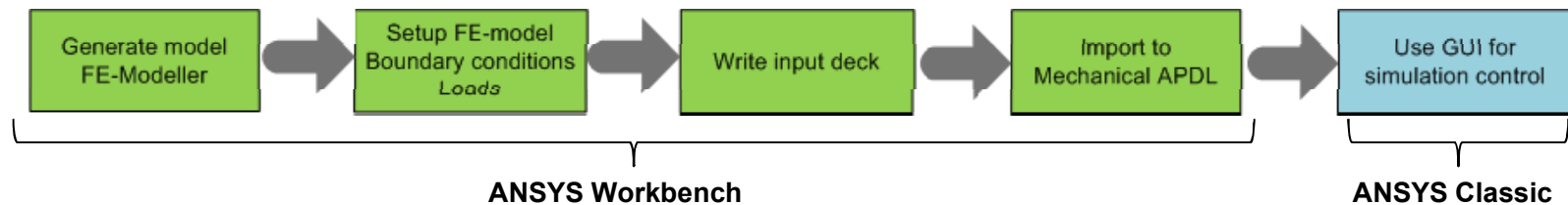


Fig. 20: Bone remodeling function (Lian et. al, 2010)

• Adaptive bone remodeling

• Steps



• ANSYS User Interface Design Language (UIDL)

- GUI implementation for parameter control of bone remodeling algorithm

• APDL macros implementing bone modeling algorithm

• APDL specials

- First implementation: ~90s per iteration for a 1.600 element test plate (solving time: ~3s)
- Modifications:
 - Avoiding *DO-loops and exploit masking and vector operations: *VMASK, *VOPER (especially for *IF and mathematical operations)
 - Using element tables to display density results
- Result: ~4s per iteration

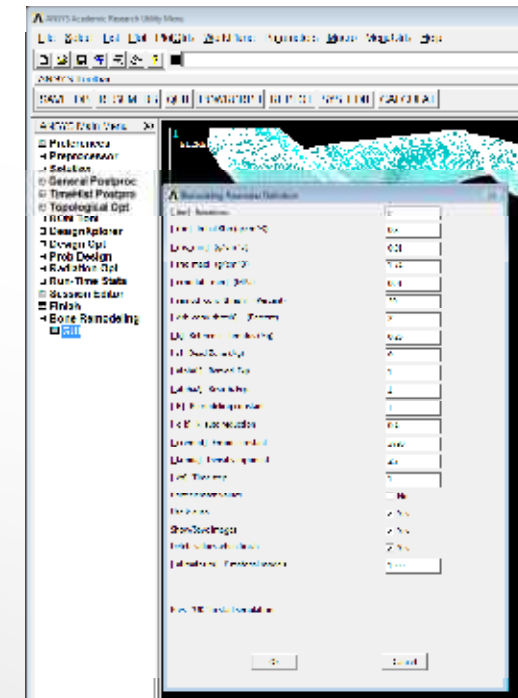


Fig. 21: UIDL GUI for algorithm control

- Adaptive bone remodeling
 - APDL specials
 - One material assigned per element for individual density change
 - Number of elements for scapula model ~380k
 - Restriction in ANSYS: 100.000 material models
 - Algorithm runtime increases by using a high number of material models
 - Discretisation of density, hence on E-module scale

$$\Delta\rho_{Sim} = \frac{\rho_{Max}}{n_{Mat}} = \frac{1.74 \text{ g/cm}^3}{1000} = 0.00174 \text{ g/cm}^3$$

ρ_{Sim} ... Density step
 ρ_{MAX} ... Maximum bone density
 n ... Number of material models

$$E_n = c \Delta\rho_{Sim}^y n \quad \text{for } n = 1 \dots n_{Mat}$$

E_n ... E-module
 c, y ... Constants

$$\rho_{MAX_ERR} = 0.05\% \quad \text{for } n_{Mat} = 1000$$

ρ_{MAX_ERR} ... Maximum density error

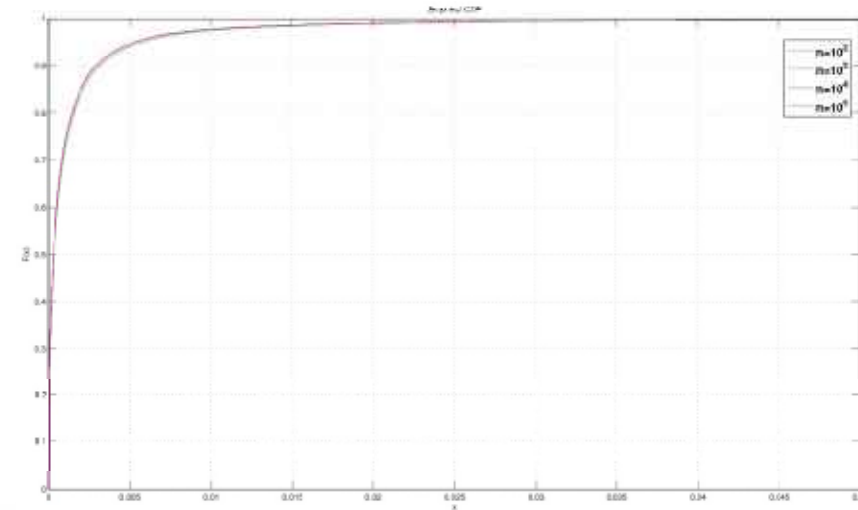


Fig. 22: CDF-Plot of SED-values

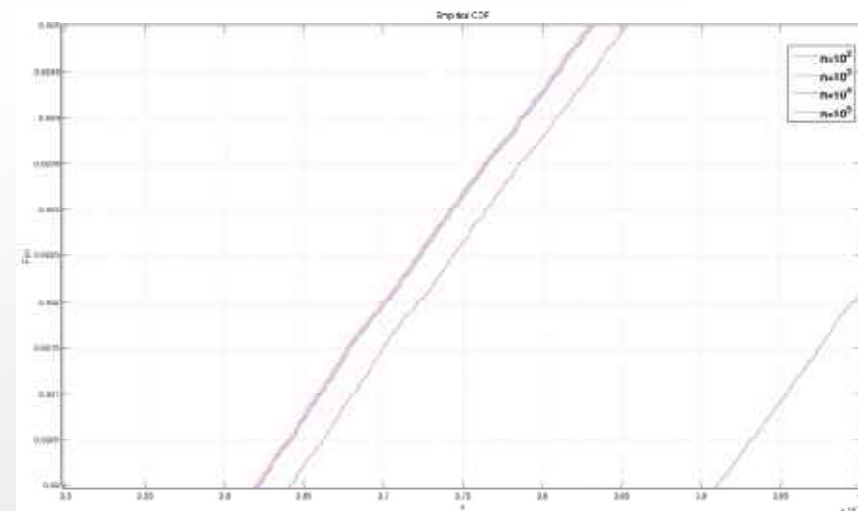


Fig. 23: CDF-Plot of SED-values (zoomed)

- Adaptive bone remodeling

- Flow diagram

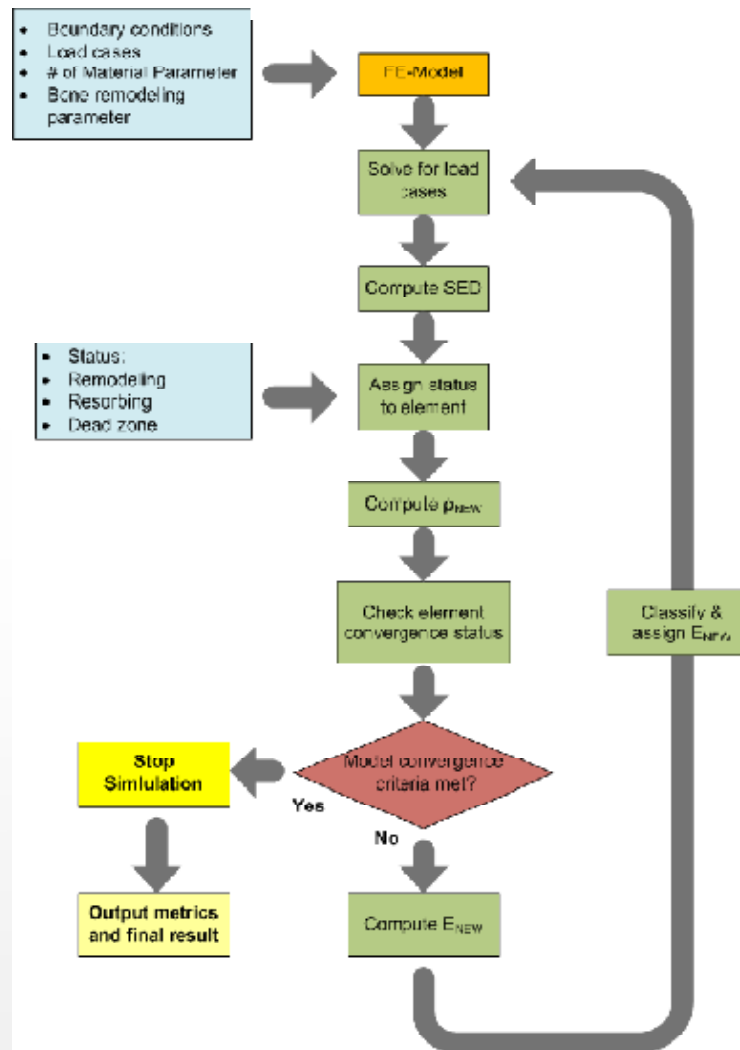


Fig. 24: Flow diagram for bone remodeling algorithm

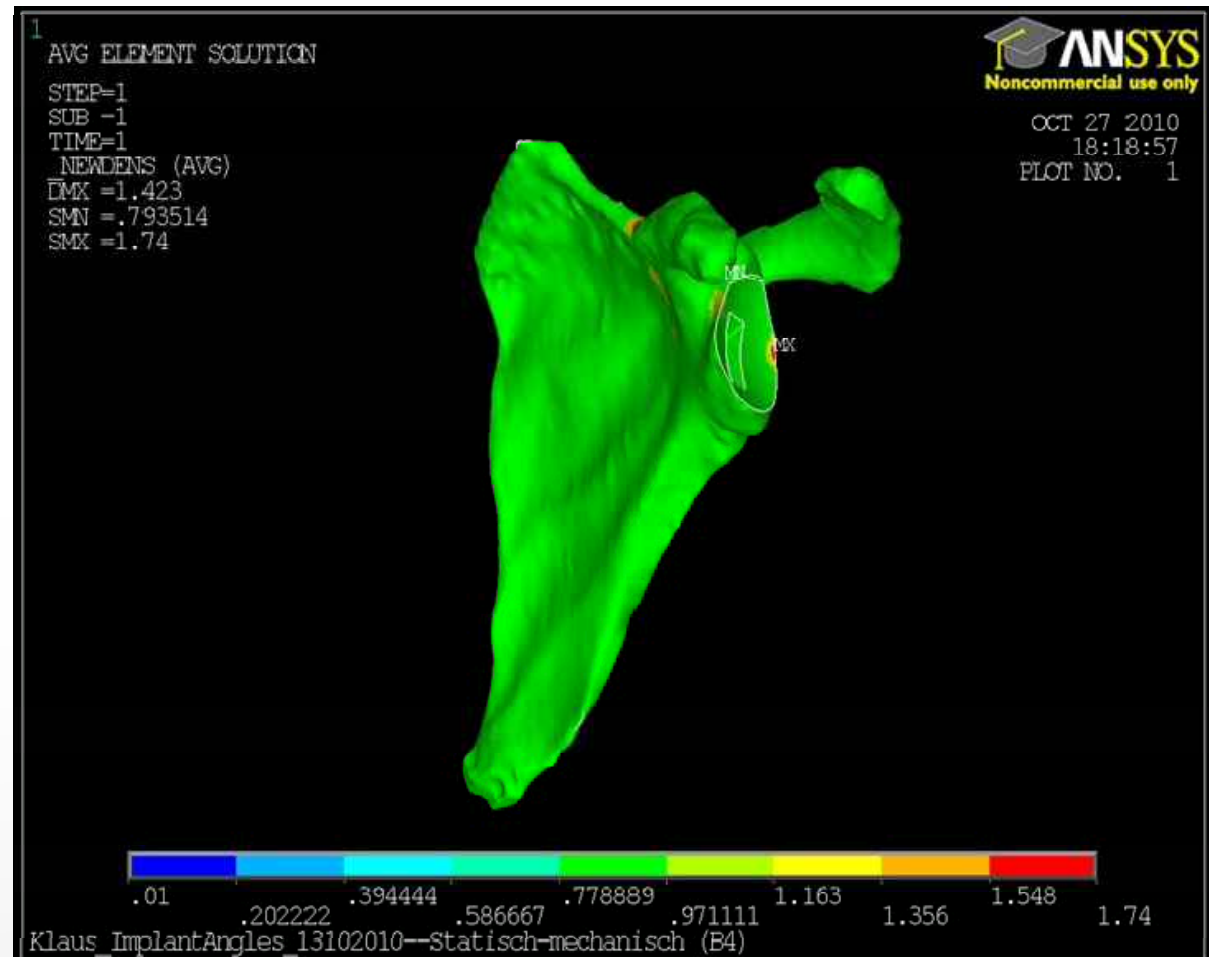
Results

• Setting

- 96k nodes, 380k elements
- Forces at 90° flexion and abduktion alternating
- Iterations: 300
- Time step: $dt=10$

• Statistics

- Solving time: 140 (avg./iter.)
- Bone remod.: 90s (avg./iter.)
- Total time incl. overhead: ~42h



Results

• Setting

- 96k nodes, 380k elements
- Forces at 90° flexion and abduction
- Iterations: 150
- Time step: $dt=10$

• Statistics

- Solving time: 138s (avg./iter.)
- Bone remod.: 95s (avg./iter.)
- Total time incl. overhead: ~42h

- First results meet expectations according to applied forces, but are subject of further validation

Fig. 25: Bone remodelled scapulaing – posterior view

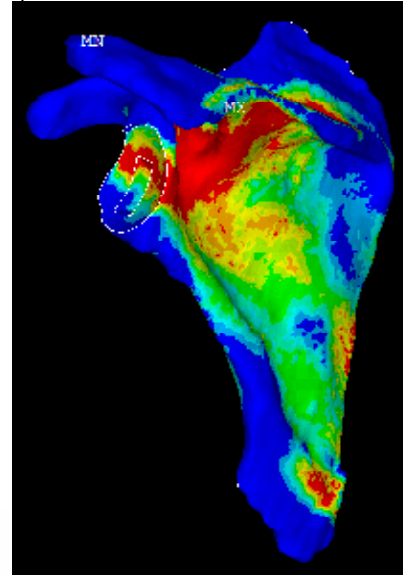


Fig. 26: Bone remodelled scapula – anterior view

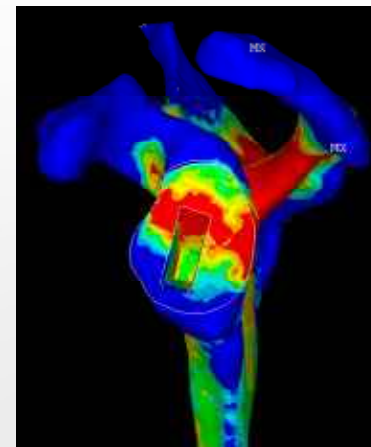
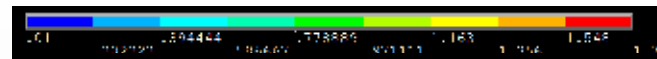
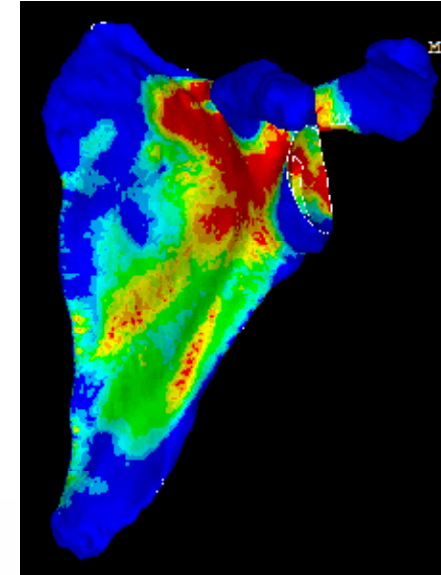


Fig. 27: Bone remodelled scapula – lateral view

Actual & Future Work

- Further testing and validation of the bone remodeling algorithm
- Assignment of bone density according to CT-Data
- Expansion of the FE-Model with humeral prosthesis part, muscular load and different prosthesis position
- Application on different anatomic shoulder models
- Comparison with a reverse shoulder implant



Fig. 28 : Reverse shoulder implant (DePuy)

Acknowledgments

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