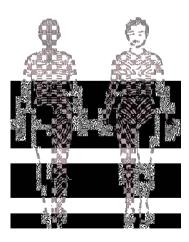
Numerical Simulation of Anisotropy Directions of Human Skin at the Macroscopic Scale

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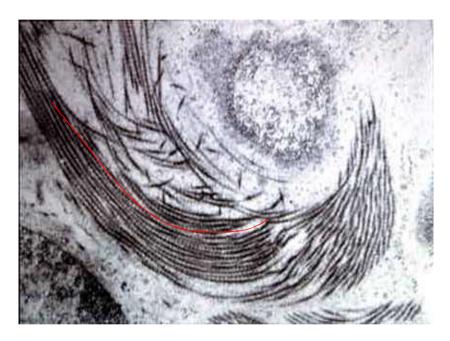
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- (2) Anisotropy direction calculation methods
 - Heat conduction-based method
 - Sketch-based Laplacian smoothing method
- (3) Mechanical Simulation on Skin
- (4) Conclusions



Motivation

Collagen fibers govern the anisotropy of soft tissue



Electron micrograph of collagen fibrils in the rat oviductal wall¹

- Mechanical properties of soft tissue ²
 - Non-linearity
 - Anisotropy
 - Softening and preconditioning
 - Pre-stress
 - Viscoelasticity

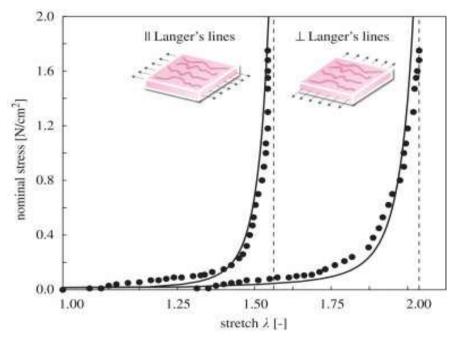
^{1.} http://millette.med.sc.edu/Lab

^{2.} Fung, Y.C., Biomechanics: Mechanical Properties of Living Tissues. Springer, 2nd edition. (1993)

Motivation

Collagen fibers govern the anisotropy of soft tissue

Mechanical behavior of Collagen fibers.



§ Collagen → strength
§ Elastin → elasticity

Uniaxial tension test of rabbit skin^{1,2}

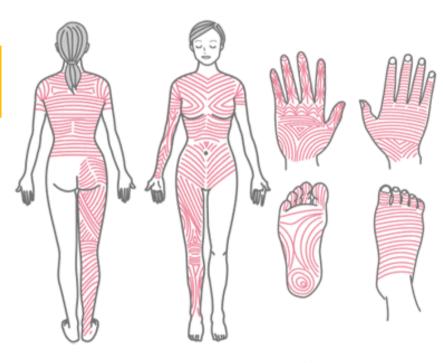
- 1. Y. Lanir, Y.C. Fung, Two-dimensional mechanical properties of rabbit skin II experimental results, J. Biomech. 7 (1974) 171–182.
- 2. Tepole et al. Stretching skin: The physiological limit and beyond. International Journal of Non-linear Mechanics, 47(2012) pp938-949.

Motivation

The anisotropy directions of skin at macro scale

Langer's Lines¹

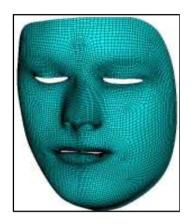
- Ø Topological lines for mapping the preferred directions of skin
- Ø The natural orientation of collagen fibers in the dermis

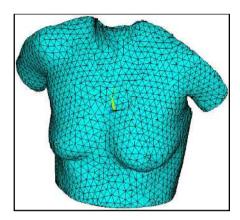


Langer's Lines²

- 1. Langer, K. 'On the anatomy and physiology of the skin'. British Journal of Plastic Surgery(1861)
- 2. http://www.beltina.org/health-dictionary/langers-lines-skin.html

Goals

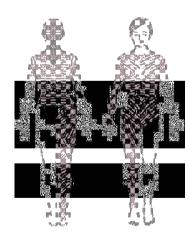


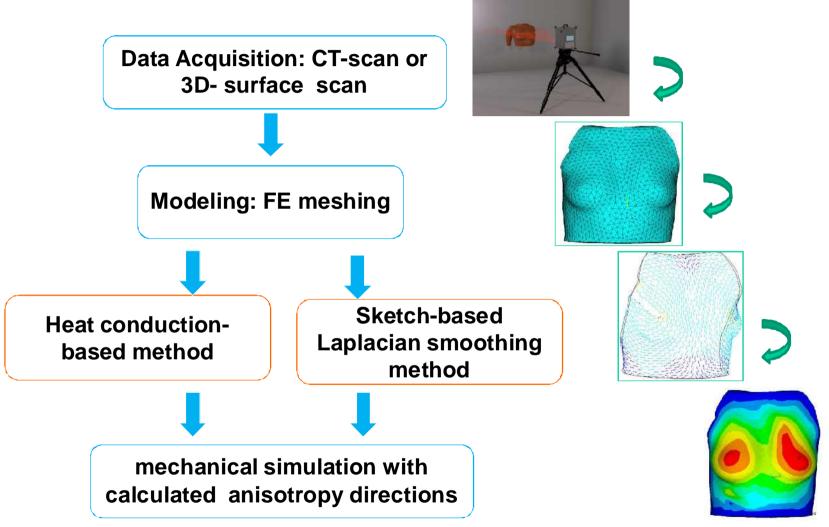


- Automatically generate the anisotropy directions for a skin model
 - I. Approaches to calculate anisotropy directions of skin.
 - Heat conduction-based method.
 - Sketch-based Laplacian smoothing method.
 - II. Implementation to the Langer's lines of skin model.
 - Mechanical simulation of skin.

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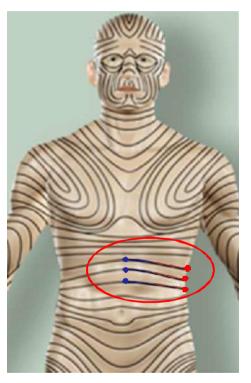




Heat conduction-based method (Method I)



Langers' lines of skin¹



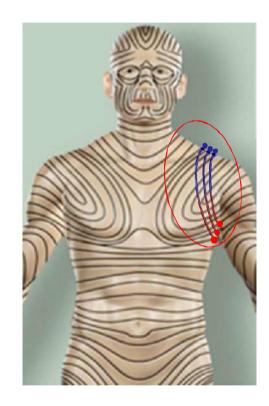
The heat flux on the abdominal region.

The heat transfers from high temperature to low temperature.

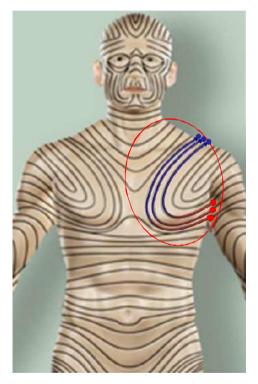
- high temperature
- low temperature

1. http://www.med-ars.it/galleries/langer.htm

Heat conduction-based method (Method I)



Heat flux on the shoulder region

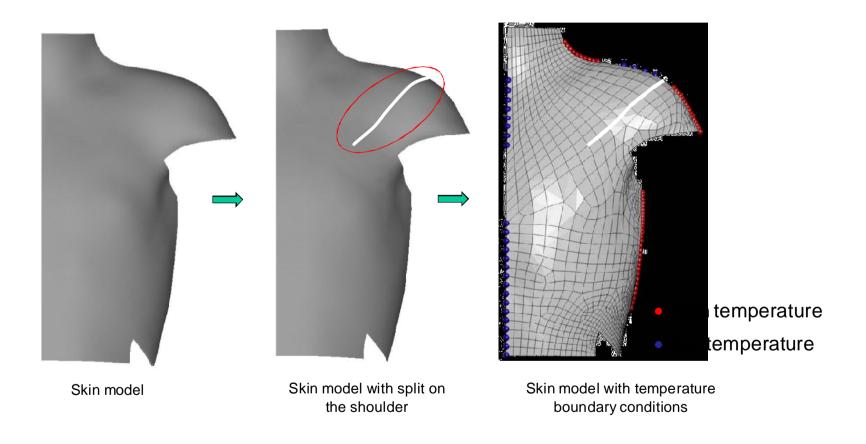


Heat flux with split on the shoulder region

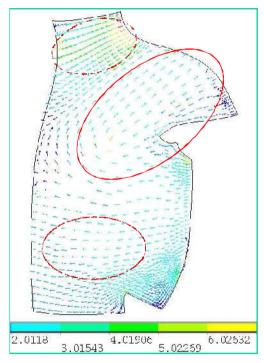
At some regions with curved skin tension lines more control is needed to get the desired curvatures.

- high temperature
- low temperature

Heat conduction-based method(Method I)



Heat conduction-based method (Method I)



Numerical results for anisotropy directions of man skin



The Langer's lines of the skin

Ø ANSYS steady state thermal conduction analysis

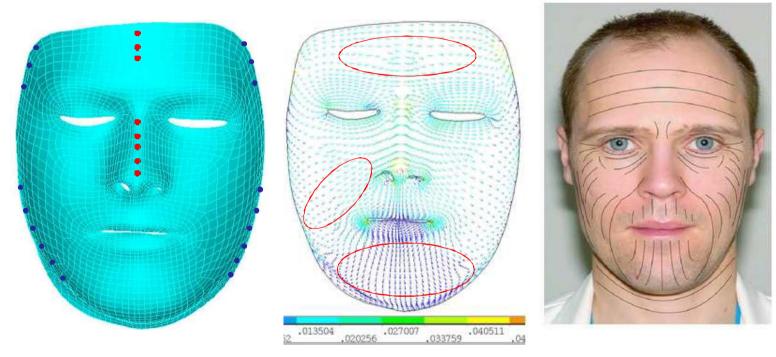
Element type: shell 131

Thermal conductivity: KXX=1

High temperature: $T_h=1$

Low temperature: $T_t = 0$

Heat conduction-based method (Method I)



face model with temperature boudaries

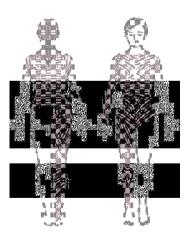
Numerical results for anisotropy directions of face model

Langers' lines on the face model¹

1. Richard Baker et al. Cutaneous Scarring: A Clinical Review, Dermatology Research and Practice, (2009)

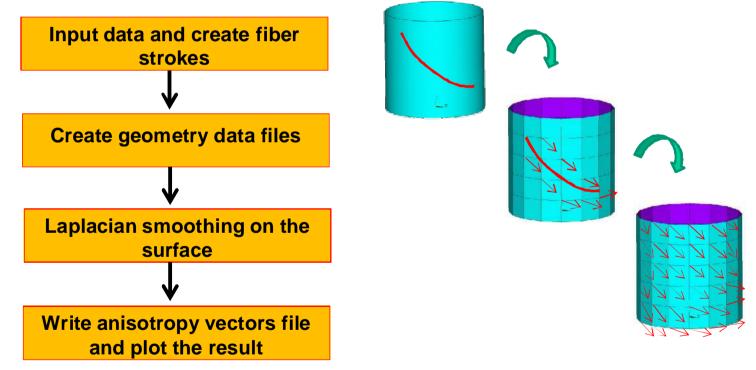
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Sketch-based Laplacian smoothing method (Method II)

▶ The sketch-based method for modeling fiber orientations: interpolates the vector field with the Laplacian smoothing method based on given strokes drawn by user^{1,2}.



Calculation flow chart

- 1. Sorkine O et al. Laplacian surface editing. (2004)
- 2. Takayama et al. The Journal of Physiological Sciences. (2008)

Sketch-based Laplacian smoothing method (Method II)

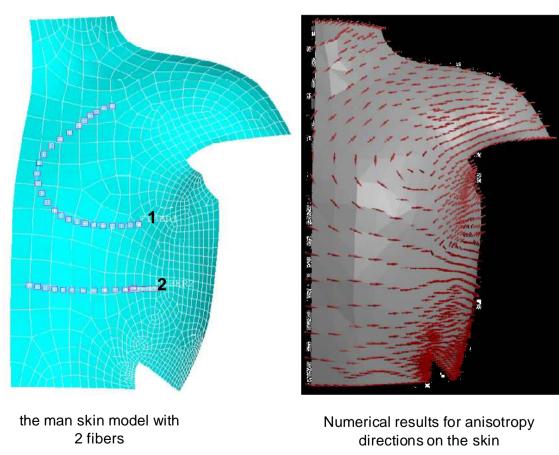
The Laplacian smoothing: minimizing the difference between anisotropy vectors in the least-squares sense under given constraints ^{1,2}.

$$\begin{bmatrix} \mathbf{L}\mathbf{V} & \mathbf{0} \\ \mathbf{C}\mathbf{V} & \mathbf{W}^c \end{bmatrix} \begin{bmatrix} \dot{\mathbf{e}}\mathbf{L} & \dot{\mathbf{u}} \\ \dot{\hat{\mathbf{e}}}\mathbf{C} & \dot{\mathbf{u}} \end{bmatrix}^2 = 0$$

- I, is the matrix defining the relation between neighboring nodes.
- C is the matrix describing the constraint in nodes of FE model.
- V is the set of all anisotropy vectors of the FE model.
- V^c is the set of constraint anisotropy vectors according to user-defined strokes.
 - 1. Sorkine O et al. Laplacian surface editing. (2004)
 - 2. Takayama et al. The Journal of Physiological Sciences. (2008)

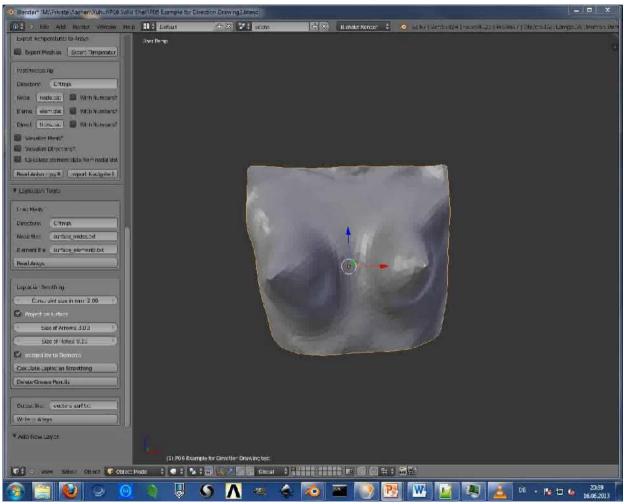
Anisotropy directions calculation methods Sketch-based Laplacian smoothing method (Method II)

▶ The sketch-based method numerical results (ANSYS and Matlab).



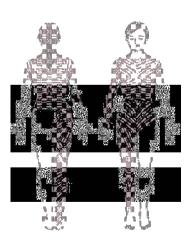
Sketch-based Laplacian smoothing method (Method II)

▶ The sketch-based method numerical results (Python and Blender).

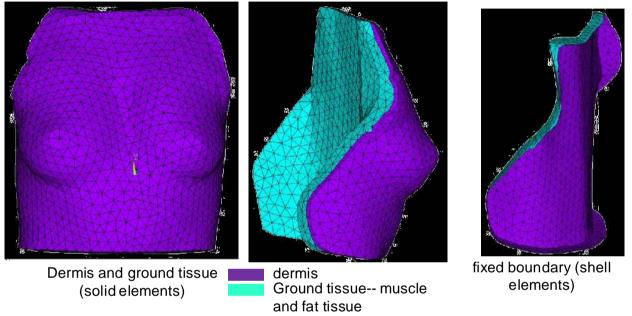


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The geometry file of female breast model

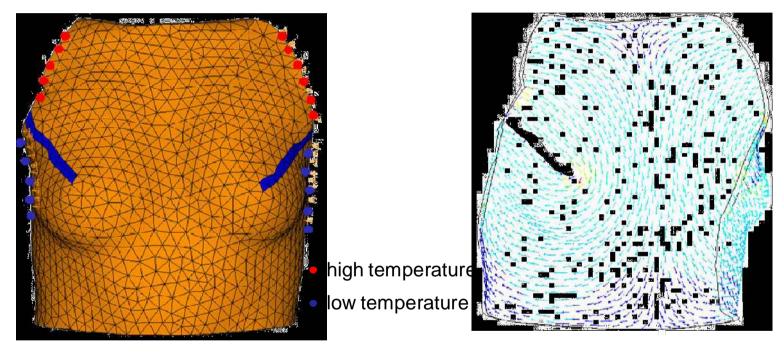


Breast model:

- Dermis is assumed as an anisotropic material with collagen fibers.
- **Ground tissue** is assumed as an isotropic material attributing the force on the dermis.
- **Fixed boundary** attribute the boundary conditions, i.e. the displacements are equal to zero.

Heat conduction-based method (Method I)

Calculation the anisotropy directions within dermis.



Temperature boundaries

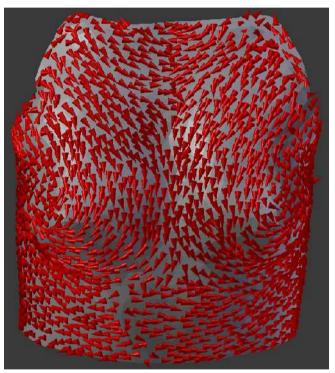
Anisotropy directions of skin

Sketch-based Laplacian smoothing method (method II)

Calculation the anisotropy directions within dermis.



User-defined strokes



Anisotropy directions of skin

Material properties of breast model

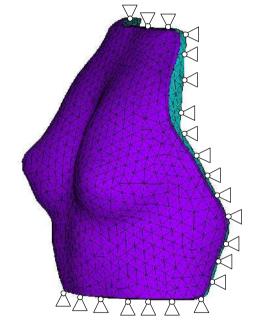
Simulation the deformation of breast model under gravity with Polyconvex model¹.

Strain energy function of polyconvex model:

$$\psi = \frac{\mu}{4} \dot{\hat{\mathbf{j}}} \frac{1}{\alpha} \left[e^{\alpha (\hat{I} - 1)} - 1 \right] + \frac{1}{\beta} \left[e^{\beta (\hat{J} - 1)} - 1 \right] \dot{\hat{\mathbf{j}}} \dot{\hat{\mathbf{j}}}$$

Material properties:

	1 1			
	μ (mPa) ²	α	β	W
skin	3.85e-3	1	3.84	0.621
Ground tissue	2.34e-3	1	3.84	0
density 1e-9 (kg/mm ³)				



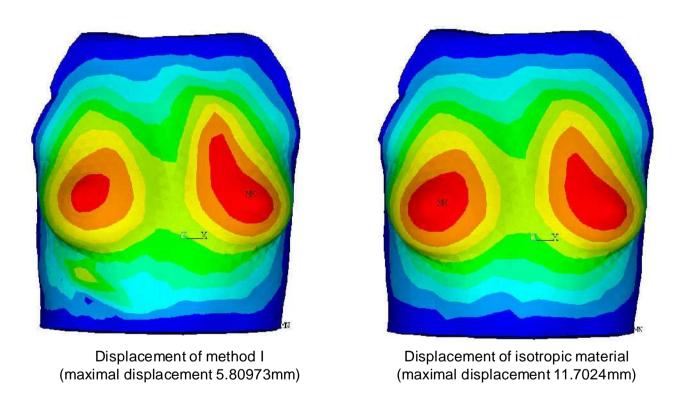
Body force and boundary conditions

acceleration 9810 (mm/s²)

^{1.} Ehret, A.E. and Itskov, M., A polyconvex hyperelastic model for fiber-reinforced materials in application to soft tissues. Journal of Material Science 42: 8853-8863,2007.

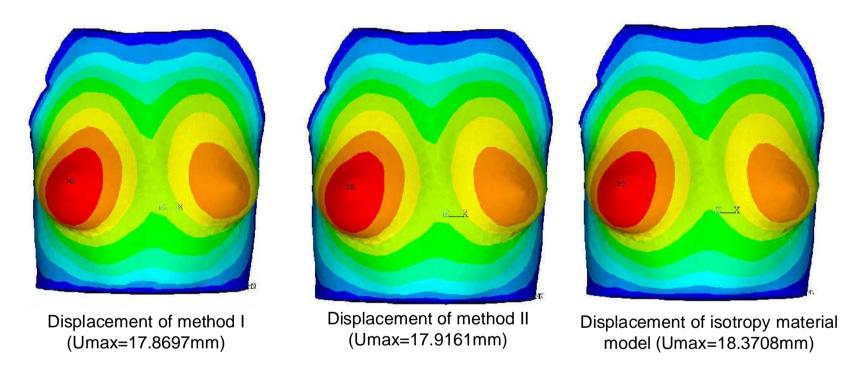
^{2.} A. Samani et al, Physics in medicine and biology (2007)

Comparison on the deformations of breast model



Ø The anisotropy directions attribute the stiffness of breast model.

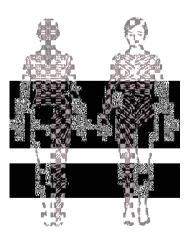
▶ Comparison on the deformations of breast model with orthotropic model.



- Ø The anisotropy directions attribute the stiffness of breast model.
- Ø These two methods both can calculate the anisotropy directions effectively.

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Comparison of the two methods

Heat conduction-based method

Advantages

- Only ANSYS software is needed for anisotropy direction calculation and further mechanical simulations.
- Anisotropy directions distribute smoothly and consistently.

Disadvantages

- The finite element model may be split in several parts.
- Definition of the temperature boundaries needs engineering experience.

Sketch-based Laplacian smoothing method

Advantages

- It is easy and fast to get the anisotropy directions and even can be used without engineering experience.
- It allows maximal control over the anisotropy directions

Disadvantages

- The implementation process should combine ANSYS and Matlab or Python.
- The directions don't distribute smoothly enough.

Conclusion

Summary

- Prediction of the anisotropy directions of soft tissue is feasible.
- Good agreement with the Langer's line data in human skin.
- Mechanical simulation of skin under gravity with anisotropy directions.

Future work

- Experimental validation of numerical anisotropy result.
- Simulation on skin model considering the properties of muscle.
- Simulation on the incision deformation.

Thank you!